

Figure 1 System Architecture Block Diagram

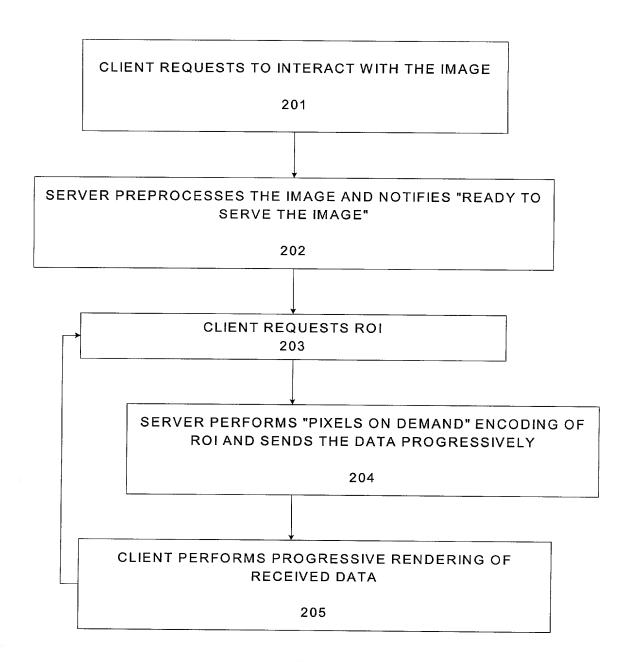


FIG. 2

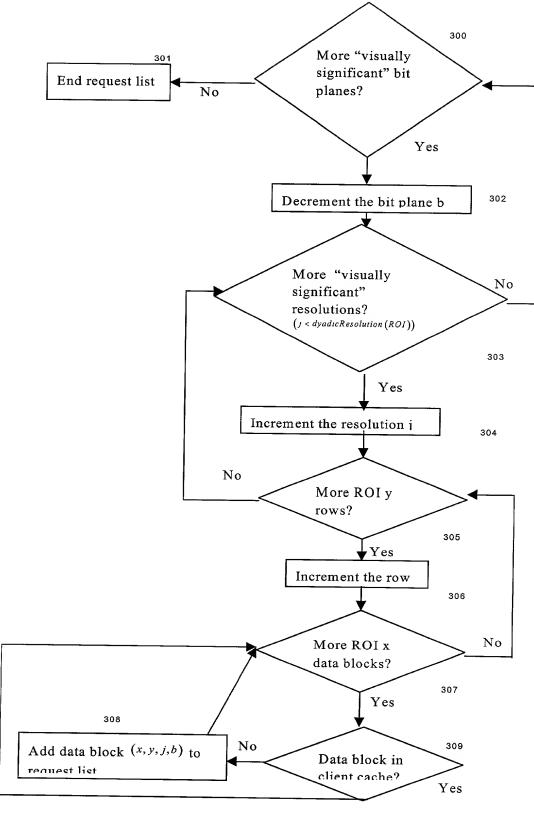


Figure 3

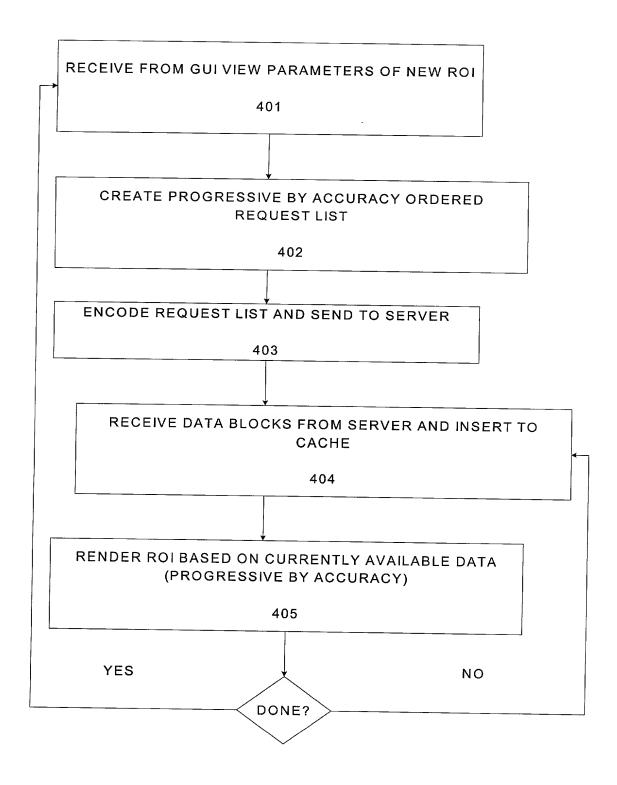


FIG. 4

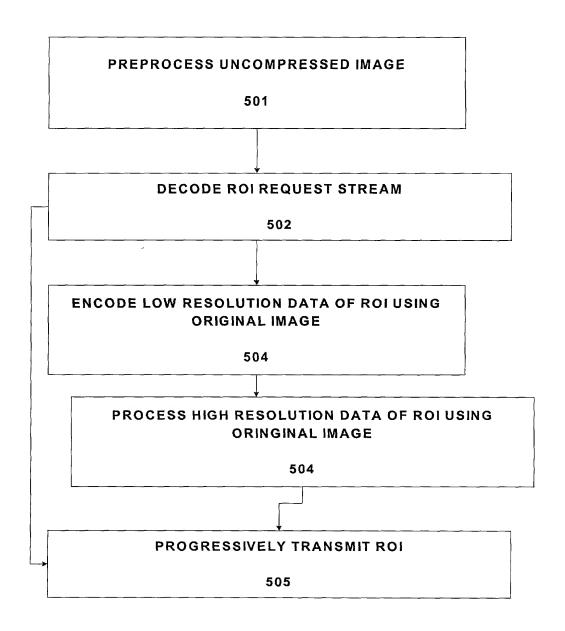


FIG. 5

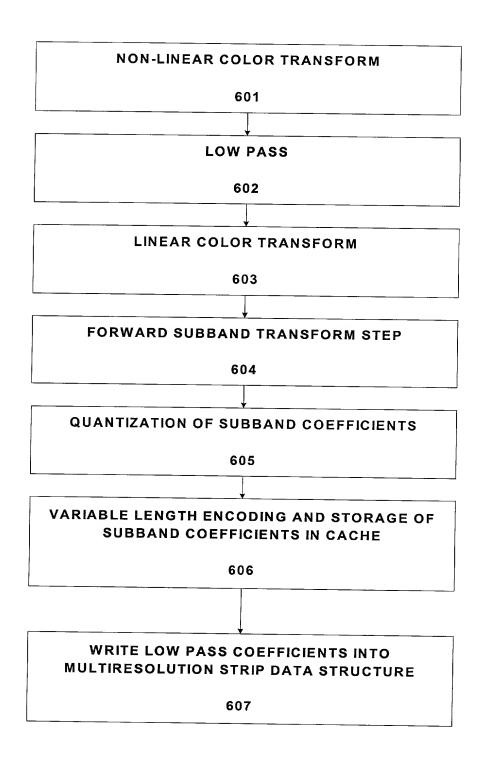


FIG. 6

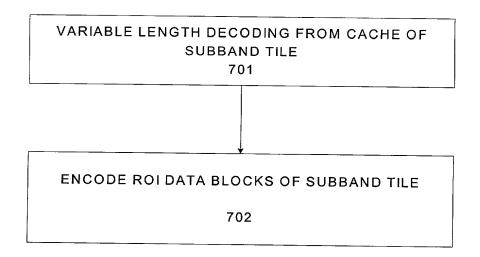


FIG. 7

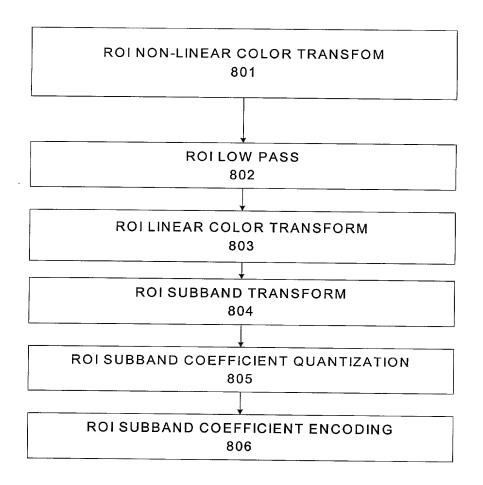


FIG. 8

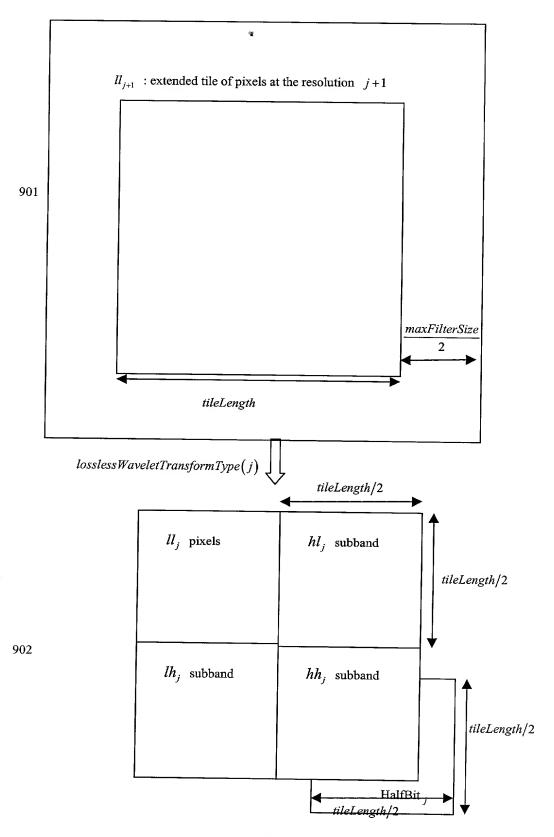


Figure 9

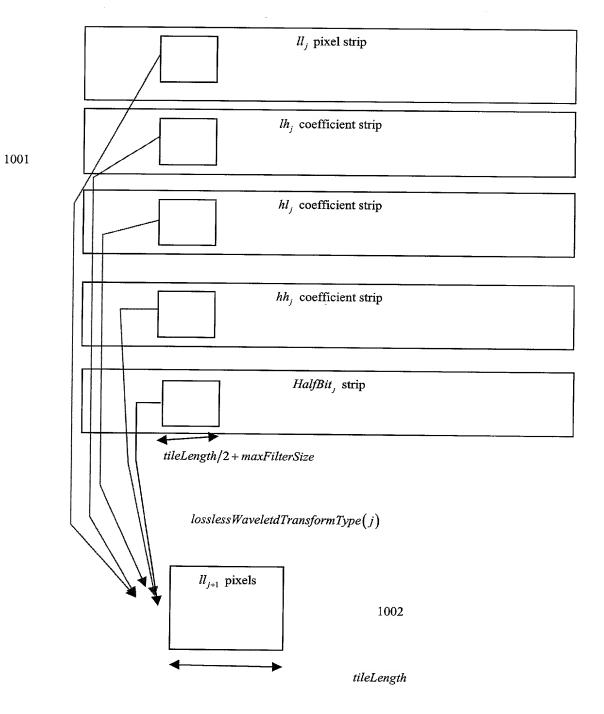


Figure 10

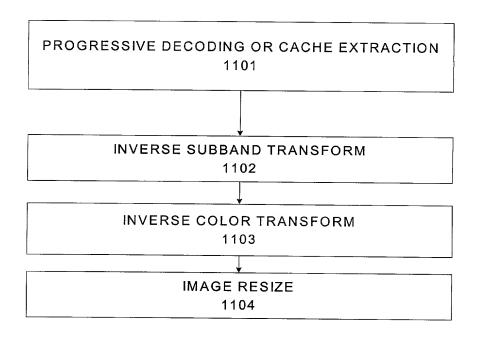


FIG. 11



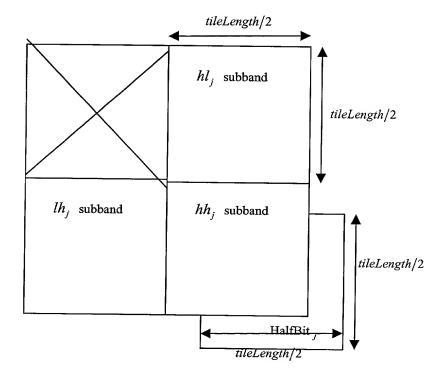


Figure 12

RGB <-> YUV Reversible Conversion

Forward:

$$Y_r = \left\lfloor \frac{R + 2G + B + 2}{4} \right\rfloor$$

$$U_r = R - G$$

$$V_r = B - G$$

Inverse:

$$G = Y_r - \left\lfloor \frac{U_r + V_r + 2}{4} \right\rfloor$$

$$R = U_r + G$$

$$B = V_r + G$$

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Figure 13

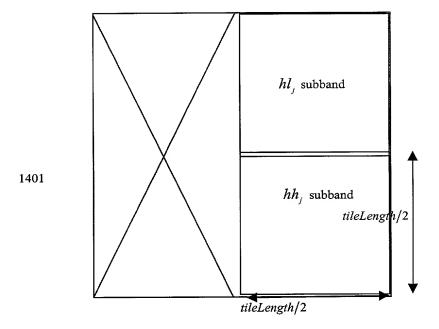


Figure 14

```
bitModel.startModel();
zeroCoefModel.startModel();
coefSignModel.startModel();
while (encoder.moreCoef()) {
  if (encoder.isCoefReported()) {
arithmetic_encode_symbol(bitModel,encoder.reportedCoefPrec
isionBit());
  else {
    if ( encoder.isCoefExactZero() );
     arithmetic_encode_symbol(zeroCoefModel,true);
    else {
     arithmetic_encode_symbol(zeroCoefModel,false);
     arithmetic_encode_symbol(coefSignModel,encoder.getCoe
fSign());
                             (a)
bitModel.startModel();
for (int i = 0; i < hBlockSize; i++) {
     for (int j = 0; j < hBlockSize; j++) {
           arithmetic_encode_symbol(bitModel,
coefHalfBit[i][j]);
     }
}
```

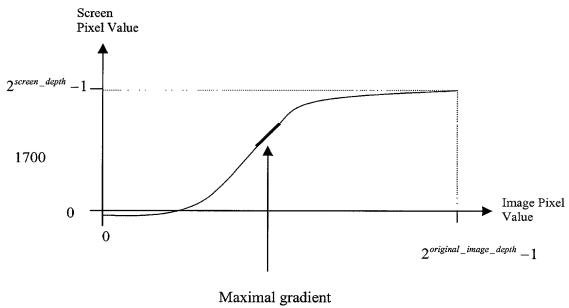
Figure 15

(b)

```
bitModel
                               .startModel();
zeroCoefModel.startModel();
coefSignModel.startModel();
decoder.initializeLSBPlaneCoefScan();
while (decoder.moreCoef()) {
  if (decoder.isCoefReported()) {
    if(decoder.isLHCoef()) {
      decoder. updateLSB (0);
    else {
     decoder.updateLSB(arithmetic_decoder_symbol(bitModel));
  else {
    if(!decoder.isLHCoef()) {
      if (!arithmetic_decoder_symbol(zeroCoefModel))
         decoder.setLSB(arithmetic decoder symbol(coefSignMode
         1));
    }
                               (a)
bitModel.startModel();
for (int i = 0; i < hBlockSize; i++) {
  for (int j = hBlockSize ; j ; j--,p++) {
    coefHalfBit[i][j] = arithmetic_decoder_symbol(bitModel);
```

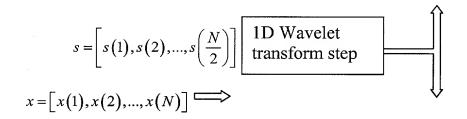
(b)

Figure 16



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Figure 17



$$d = \left[d(1), d(2), \dots, d\left(\frac{N}{2}\right)\right]$$

$$X = \begin{bmatrix} x(1,1) & x(1,2) & \cdots & x(1,N) \\ x(2,1) & x(2,2) & \cdots & x(2,N) \\ \vdots & \vdots & \ddots & \vdots \\ x(M,1) & x(M,2) & \cdots & x(M,N) \end{bmatrix}$$

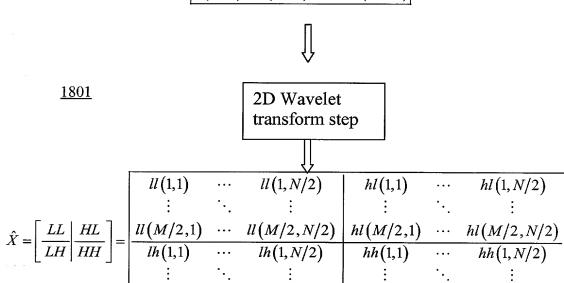
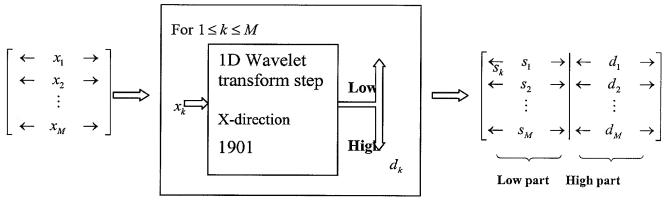


Figure 18



Input matrix *X*

Temporal matrix $T = [S \mid D]$

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Figure 19

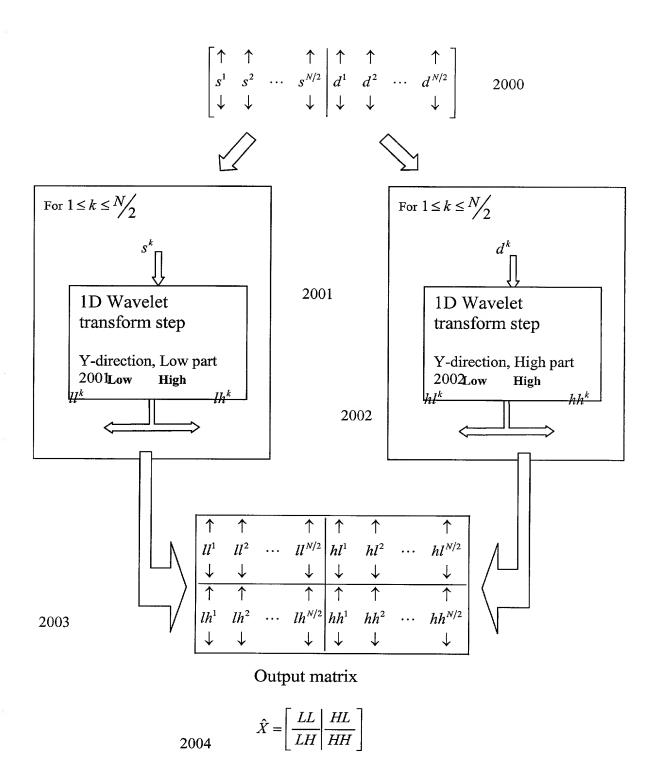


Figure 20

Let I be the original Image,

$$ZD \text{ Wavelet transform step} \qquad \qquad \boxed{\frac{LL_0}{LH_0} \frac{HL_0}{HH_0}}$$
For $0 < i < Levels$

$$X_i = LL_{i-1} \qquad \qquad \boxed{\frac{LL_i}{LH_i} \frac{HL_i}{HH_i}}$$

LLLeveis-1	HL_1	HL_0
LH_1	HH_1	
LH_0		HH_0

Figure 21

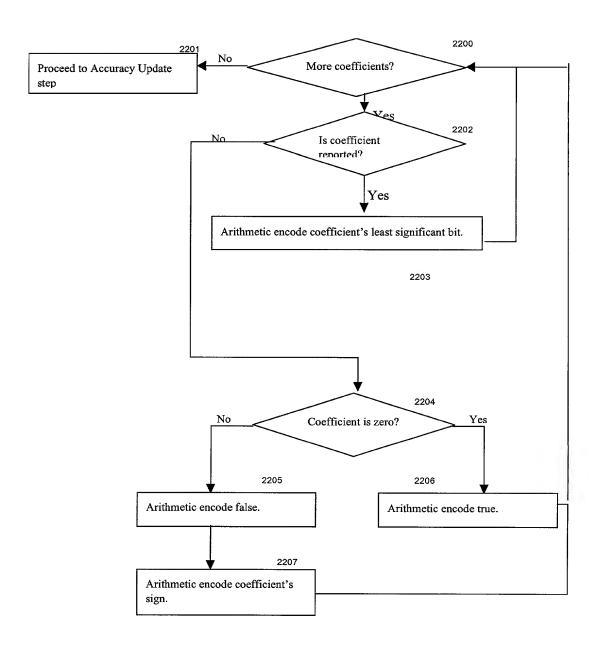


Figure 22

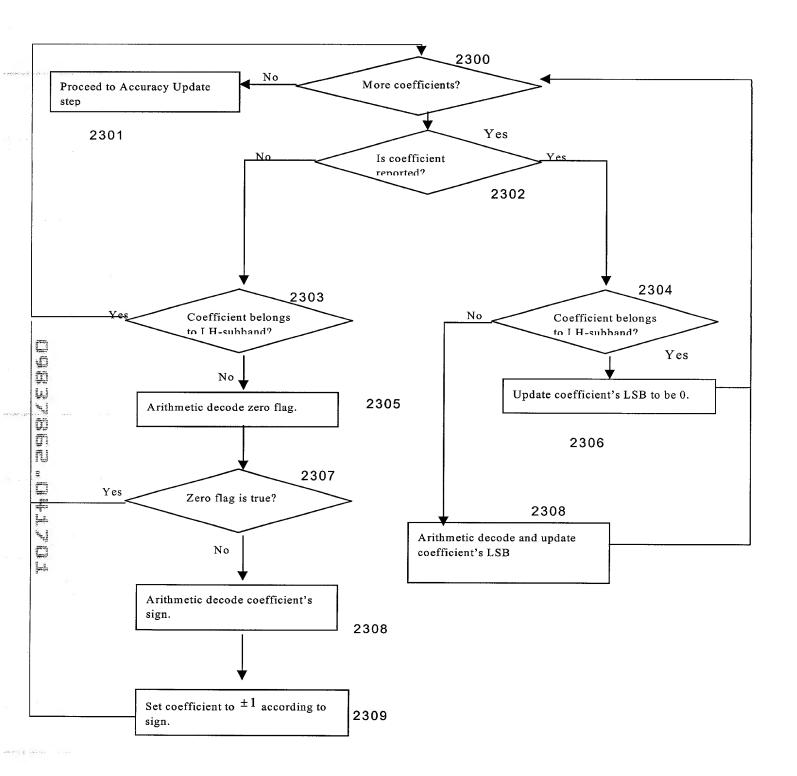


Figure 23

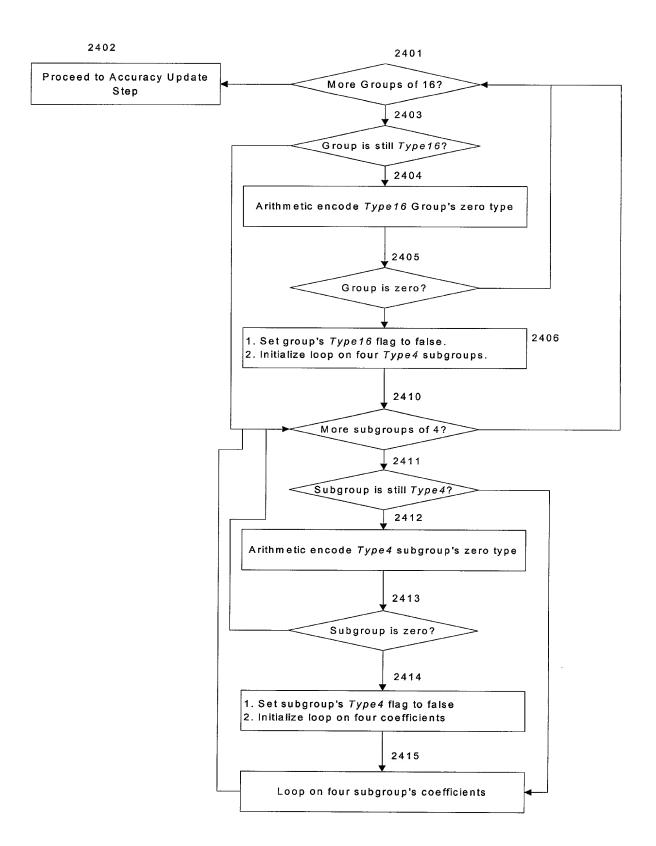


FIG. 24

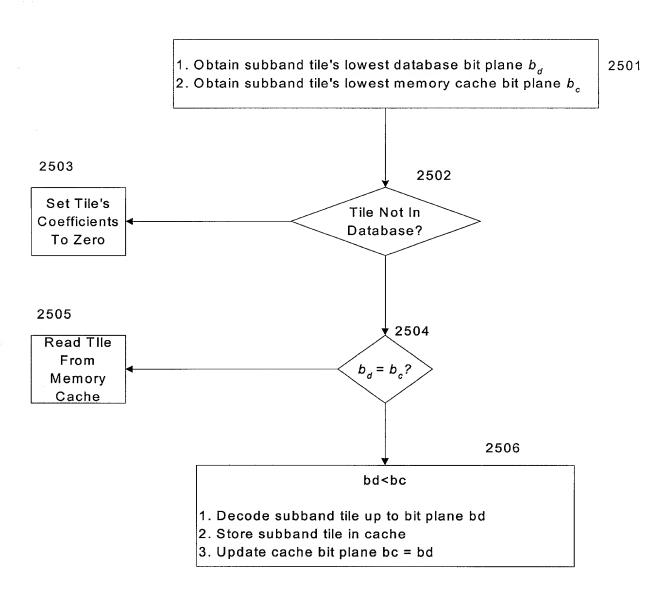


Fig. 25

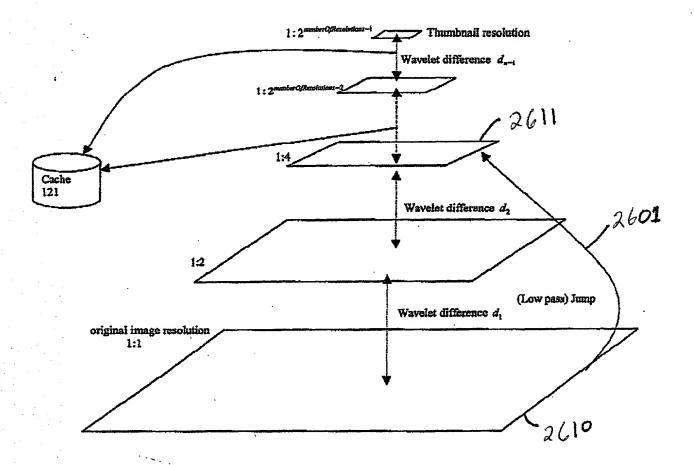


Figure 2/, Preprocessing multiresolution structure